OPERATION AND INSTALLATION MANUAL





Rockwell Automation Encompass Product Partner Global

Corporate Headquarters 9440 Carroll Park Drive San Diego, CA 92121 Phone: (858) 278-2900 FAX: (858) 278-6700 Web-Site: http://www.hardysolutions.com

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CHAPTER 1 - OVERVIEW

Allen-Bradley License

Under license from The Allen-Bradley Corporation, Hardy Process Solutions Inc. has developed a Remote I/O Interface for the HI 2151 Weight Controller. The HI 2151WC is a general purpose industrial and process weighing instrument for use in a wide variety of applications including filling, dispensing, batching, and monitoring rate of flow by weight. The instrument includes numerous features and technologies including up to eight setpoint relays, 1,000,000 counts of resolution, Secure Memory Module for backup of critical calibration data, and WAVERSAVER[®], the ability to ignore plant and process mechanical noise to quickly arrive at stable weight readings.

Hardy Process Solutions worked with substantial customer input and Allen-Bradley to identify that the remote I/O communications network best matched the needs of system integrators and end users for industrial and process applications. The interface is fast, field proven, requires minimal wiring, requires no special software drivers, and is standard on many Allen-Bradley programmable controllers. Setting each address and baud rate in the instrument, connecting three wires, and writing some ladder logic is all that is needed to begin communicating weighing parameters to and from an HI 2151WC controller.

Each Hardy HI 2151WC represents a quarter (1/4) rack of discrete I/O (32 bits in the PLC Output and Input image files) to the scanning PLC and supports both discrete and block transfers. The PLC continually exchanges 32 bits of its PLC Input Image Table and 32 bits of its Output Image Table with each 1/4 rack device. In a 1771 I/O Rack, these bits would normally be transferred from and to discrete input and output modules. For the weight controller, the Output Image bits are used to send commands to the weight controller and the Input Image bits return weight data and scale status bits. These actions are referred to as "discrete writes and "discrete reads". The user is also able to exchange blocks of data with a 1/4 rack device via Block Transfer instructions in the PLC ladder logic program. These commands are referred to as "block writes" and "block reads".

The host programmable controller can access all configuration and weighing parameters in the HI 2151WC, including performing scale calibration. The HI 2151WC can be used as a local display and keyboard for weighing parameters, or function as a blind controller properly digitizing the load cell signal and providing responsive setpoint control.

Using the Remote I/O interface shortens development time and provides the most functional weighing interface available for your Allen-Bradley programmable controller. Before starting system design, you

should also read the Installation and Operation manual of the HI 2151WCs.

	Information contained in this manual is subject to change. Always check the latest version of this manual at our web site (http://www.har- dysolutions.com) before beginning system design. This product incor- porates technology which is licensed by Allen-Bradley Company Inc. Allen-Bradley does not technically approve, warrant or support this product. All warranty and support for this product is provided by Hardy Process Solutions Inc. PLC [®] , PLC-2 [®] , PLC-3 [®] , PLC-5 [®] , SLC500 [®] Series are registered trademarks of the Allen-Bradley Company, Inc.		
Common Applications	The HI 2151WC series can be used in conjunction with Allen-Bradley programmable controllers to tackle a variety of process control needs. The most basic use of the interface is to simply allow the programmable controller to read weight data from one or more HI 2151WC series weight controllers. In addition to reading weight some other applications are:		
	 Filling Dispensing Batch Weighing Control Monitoring Rate of Flow Evaluating Totalized Weight Check Weighing Weight Level Alarming 		
NOTE:	There are two standard and six optional setpoint relays which provide control of ingredient weighments and weight level alarming.		
Monitoring Weighing Parameters	The HI 2151WC series weight controllers are capable of calculating five types of weight data, including the standard Gross and Net weights. In addition to the standard Gross and Net weights there are three options such as Peak Force, Totalized Weight (block transfer only), and Rate-of-Change or mass flow rate entering or leaving a ves- sel.		
Short Glossary of Terms	 Gross Weight - is used to describe the total weight of the container and the contents. Net Weight - is the weight of the contents of the container only. Tare Value - The action of adjusting out the known weight of the container from the total indicated weight, so that the indicator reads weight directly. Dead Load - The weight of the vessel and other equipment which will be ignored during zero calibration. 		
Tare Value	Current Gross Weights becomes the Tare value by pushing the Tare Push Button on the front panel of the HI 2151WC, remote functions contact closure, discrete write or block transfer command by the PLC,		

or can be entered as a numeric value via the keypad on the front panel of the HI 2151WC. This new tare value is the reference point for Net Weight.

$$TV = G - N$$

TV = Tare Value (weight) G = Gross Weight N = Net Weight

CHAPTER 2 - INSTALLATION

Remote I/O Board Cable Termination Dip Switch Configuration

About Cable Termination Weight controllers are connected to a cable in daisy-chain fashion and are referred to as "nodes". A Daisy Chain is a hardware configuration in which devices are connected one to another in a series. The end nodes on the daisy chain require termination resistors. The Remote I/O board provides the S1 Dip Switches which are used for cable termination based on the baud rate. (See Table 2-1) The S1 Dip Switches are only used on the last device in the daisy chain. For all other devices on the daisy chain both dip switches should be set to OFF. (See Fig. 2)

BAUD	TERMINATION	MAX NODES	MAX LENGTH	SWITCH 1	SWITCH 2
57.6 K	150 Ohms	16	10,000 Feet	ON	OFF
115.2 K	150 Ohms	16	5,000 Feet	ON	OFF
230.4 K	82 Ohms	32	2,500 Feet	OFF	ON

TABLE 2-1: CABLE TERMINATION REQUIREMENTS

NOTE:

Setting the Cable Termination Dip Switches

- *Refer to your Allen-Bradley PLC-2, PLC-3, PLC-5 and SLC 500 manuals for the maximum number of nodes available.*
- Step 1. For all RIO board options (except for the last device) make sure the dip switches are set to the OFF position. (See Fig. 2-1)



FIG. 2-1 REMOTE I/O S1 DIP SWITCH SETTINGS (DEFAULT)

The factory default setting is for both switches to be turned OFF. Also note that the dip switches in Figure 2-1 have been rotated for illustration purposes.

Step 2. On the last RIO board in the daisy chain, select the desired switch settings in Table 2-1 for Baud Rate.

NOTE:

The cable lengths used in Table 2-1 are maximum lengths that can be used in the daisy chain.

Installing the RIO Option Board

- Step 1. With the 26 pins facing down, align the RIO Option Board over the connector on the A/D board. In either option slot.
- Step 2. Gently slide the pins into the connector until it stops.
- Step 3. Attach the board to the standoffs by installing the four screws to the standoffs.
- Step 4. Connect the cable to the 6 pin connector on the RIO board. The 6 pin connector on the RIO option board is used for all Remote I/O connections. Pin definitions:
 - Pin 1BLUE (1/2 of twisted pair)
 - Pin 2 SHIELD (outer braided shield)
 - Pin 3 Clear (1/2 of twisted pair)
 - Pin 6 Ground (Case)

CHAPTER 3 - SETUP

Remote I/O Setup

Bargraph LEDS Secondary Functions (HI 2151/ 20WC only) While the RIO menu is displayed, the Bargraph LEDs have the following secondary functions.

A. The Zero Track LED displays the status of the "Green LED" on the RIO.

- On = Run
- Off = Off Line
- Flashing indicates either program mode or frequent retries.
- B. The Motion LED indicates Self-Test. Self-Test is executed when the instrument powers up. The Motion LED flashes continuously if the Self-Test fails.
- C. The Ctr Zero LED illuminates if communications fail. This failure can be caused by improper cabling, incorrect selection or improper use of termination resistors.
- D. The Total LED is used for factory testing and illuminates when the status byte is set to 7.



FIG. 3-1 FRONT PANEL/HI 2151/20WC

NOTE:

The bargraph LED Secondary functions above are for the HI 2151/20 only. The setup procedures in the remainder of this chapter are for both the HI 2151/20 and the HI 2151/30.

Setup Procedures	Step 1.	Enter the Option Menu by pressing the 7/Option button. (Dis- play shows the first option available)
	Step 2	Press the up arrow until RIO is displayed on the screen
	Step 2. Step 3.	Press the Enter button two times. (Display shows the cur-
	1	rently selected Baud Rate value)
	Step 4.	Use the up or down arrow to select a baud rate 57600, 115200 or 230400 (Display shows the currently selected value)
	Step 5	Press the Enter button two times
	Step 5.	If a change is necessary press the Test/Clr button
	Step 7.	Use the numeric buttons and enter the PLC rack number.
	···· I · ·	(Maximum 63)
NOTE:	The rack i PLC. You	number is displayed in decimal on the weight controller, and octal in the cannot use 0 for the PLC rack number.
	Step 8.	Press the Enter button.
	Step 9.	Press the Enter button to see the quarter number. (Display shows the currently selected value)
	Step 10.	If a change is necessary, press the Test/Clr button.
	Step 11.	Use the numeric buttons and enter the PLC quarter number (maximum 3).
NOTE:	The quart Q tr $1 = P$	er rack number in the PLC is displayed in decimal. $Qtr 0 = PLC$ Group 0, LC Group 2, $Qtr 2 = PLC$ Group 4, $Qtr 3 = PLC$ Group 6.
	Step 12.	Press the Enter button.
	Step 13.	Press the Enter button to view last quarter status.
	Step 14.	Use the up or down arrow buttons to select Yes or No to indi- cate whether or not this is the last quarter of this rack cur- rently in use
	Step 15	Press the Enter button
	Step 16.	Press the Exit button.
	Step 17.	Press the Exit button.
NOTE:	If any dat	a was changed a Reboot is required.
	Step 18.	Now power-down the instrument and re-apply power to have new menu selections activated. In addition, you must perform a manual or auto configuration of the PLC.
Display Error Codes	These di 2151WC	splay error codes are in addition to those listed in the HI C manual.
ERR 33	Invalid o	quarter number entered. Select a value from 0 - 3.
ERR 34	Invalid 1	ack number entered. Select a value from 1 - 63.
ERR 52	Too mar	ny serial ports are installed.
Blind Unit Operation		

Setup

About Blind Units	An HI 2151WC Weight Controller that cannot be programmed or con- figured from the front panel is a blind unit. In a blind unit, the Remote I/O parameters are configured using both the interior and exterior dip switches. (See Tables below)
NOTE:	You must power-down and power up the instrument to have new switch positions acti- vated. You must also perform a manual or auto configuration of the PLC.
Blind Unit Configuration	 Step 1. Disconnect the power cord from the instrument. Step 2. Set the Interior Dip Switches. (See Table 3-1)

INTERIOR DIP SWITCHES			
Switch Position - S2 which is located on the Power/Relay board			
1	n/u		
2	n/u		
3	n/u		
4	n/u		
5	last quarter in rack ON = Yes OFF = No		
6	Blind Unit ON = Yes OFF = No		
7	A1 (See Binary Baud Rate Table 3-1)		
8	A0 (See Binary Baud Rate Table 3-2)		

 TABLE 3-1: INTERIOR DIP SWITCHES

BINARY BAUD RATE			
A1	A0	BAUD	
0	0	57.6K	
0	1	115.2K	
1	0	230.4K	
TABLE 3-2:			

ON = 1OFF = 0

Remember to select the appropriate jumper positions on the Remote I/O Option Board.

EXTERIOR DIP SWITCHES		
Switch Position - S3 which is located on the Rear Panel		
1	B5 (32)	
2	B4 (16)	
3	B3 (8)	
4	B2 (4)	
5	B1 (2)	
6	B0 (1)	
7	C1	
8	C0	

TABLE 3-3: EXTERIOR DIP SWITCHES

B0 through B5 represent a binary value for rack # from 1 to 63.

BINARY QUARTER #				
C1	C0	Quarter #		
0	0	0		
0	1	1		
1	0	2		
1	1	3		

TABLE 3-4: BINARY QUARTER NUMBER

ON = 1OFF = 0

NOTE:

CHAPTER 4 - DISCRETE TRANSFERS

Discrete Writes

The PLC places two sixteen bit words in the Output Image Table which are read by the HI 2151WC weight controller. The second word defines which weight data the HI 2151WC should place in the Input Image Table for the PLC to read. The first word is reserved for future use. Programs should send all zeros for the first word to avoid conflict with future revisions of the command set.

Structure of the Two Words in the PLC Output Image Table

	bits: 15-12	bits: 11-8	bits: 7-4	bits: 3-0
First Word of the Quarter	reserved for future use			
Second Word of the Quarter	bit shift	weight parameter	1st status byte	2nd status byte

 TABLE 4-1: DISCRETE WRITE - 2 WORDS (16 BITS EACH)

Bit	Shift	A number from 0 to 4 specifies the number of bits to shift the 16 bit window from the right of the internal 20 bit value. This sixteen bit win- dow is the weight value that will be placed in the PLC Input Image Table. See the section on resolution for additional information. Once the sixteen bit value is read by the PLC, it can be multiplied by the fac- tor shown below to yield the actual weight value.
		0 = No shift, the lowest 16 bits are transferred. 1 = Shift one digit, multiply by 2 to achieve actual weight value 2 = Shift two digits, multiply by 4 to achieve actual weight value 3 = Shift three digits, multiply by 8 to achieve actual weight value 4 = Shift four digits, multiply by 16 to achieve actual weight value
We	eight Parameter	Select either Gross weight, Net weight, Rate-of-Change (mass flow), peak force (or peak weight), or Test weight to be placed in the PLC Input Image Table.
NOTE:		All weight parameters are in the units (lbs., kgs.) used during calibration.
		0 = Gross Weight (Standard) 1 = Net Weight (Standard) 2 = Rate-Of-Change (mass flow) (Optional) 3 = Peak weight or force (Optional) 4 = Test weight (an arbitrary incrementing value)

Status Byte	Select two of the status bytes below to be placed in the PLC Output Image Table. Definitions of the status bits contained in each status byte:
	 0 = Relay Status Byte 1 = Remote Function Status Byte 2 = Indicator Group 2 Status Byte 3 = Indicator Group 1 Status Byte 4 = Dipswitch Settings (exterior) Status Byte 5 = Dipswitch Settings (interior) Status Byte 6 = Acquire Tare (Set tare value = current gross weight) 7 = Lights test LED (see RIO Setup menu) 8 = MSB of 24 Bit Weight Value 0-3 = 4 bits of weight data (16-19) 4-7 = Sign Bits (20-23) 9 = Sync Pulse 0-7 = This byte increments every 50 milliseconds
Example	Placing a 0000 (Hex) for the first word and a 0123 (Hex) for the second word in the PLC Output Image Table will cause the HI 2151WC to place the least significant sixteen bits of the internal 20 bit net weight value and Indicator Groups 1 and 2 Status Bytes in the PLC Input Image Table.
Discrete Reads	the HI 2151WC places the weight and status information, specified in the last discrete write command in the PLC Input Image Table. The

the last discrete write command, in the PLC Input Image Table. The data is arranged as shown in Table 3-2.

bits:	15-8	7-0
First Word of the Quarter	MSB of weight parameter	LSB of weight parameter
Second Word of the Quarter	1st Status Byte	2nd Status Byte

TABLE 4-2: DISCRETE READ - 2 WORDS (16 BITS EACH)

NOTE:

Negative values are sent in "two's complement form".

0 = Relay Status	bit 0	Relay #8 status (on/off)
Byte	bit 1	Relay #7 status (on/off)
-	bit 2	Relay #6 status (on/off)
	bit 3	Relay #5 status (on/off)
	bit 4	Relay #4 status (on/off)
	bit 5	Relay #3 status (on/off)
	bit 6	Relay #1 status (on/off - Notice relays 1 and 2
		are not in numerical sequence)
	bit 7	Relay #2 status (on/off - Notice relays 1 and 2
		are not in numerical sequence)

1 = Remote	bit 0	Force display to Rate-of-Change mode
Function Status	bit 1	Add current net weight to total
Byte	bit 2	Hold value on display
2	bit 3	Hold option card updates
	bit 4	Force display to Net Weight mode
	bit 5	Toggle lbs/kg
	bit 6	Acquire Tare
	bit 7	Print Request (RS232 and BCD ports)
2 = Indicator Group	bit 0	Weight currently displayed in pounds units
2 Status Byte	bit 1	Zero Track feature enabled
	bit 2	Reserved for future use
	bit 3	Current Gross Weight = 0
	bit 4	Weight in motion, i.e. changing
	bit 5	Gross Weight currently displayed
	bit 6	Net Weight currently displayed
	bit 7	Weight currently displayed in kilogram units
3 = Indicator Group	bit 0	Rate-of-Change currently displayed
1 Status Byte	bit 1	Setpoint Relay #2 active
,	bit 2	Setpoint Relay #1 active
	bit 3	Peak Force (weight) currently displayed
	bit 4	Totalized weight currently displayed
	bit 5	Reserved
	bit 6	Excitation Monitor Error
	bit 7	Reserved
4 = Dipswitch	bit 0	RE-calibrate toggle
Settings (exterior)	bit 1	Option menu keypad lockout
Status Byte	bit 2	Setpoint menu keypad lockout
,	bit 3	Lb/Kg. Net/Gr. Tare. Zero keypad lockout
	bit 4	Zero tracking enable
	bit 5	Reserved for future use
	bit 6	RS232 command lockout
	bit 7	Multi-Drop enable
NOTE:	If Blind Me	ode dip switches status not visible.
NOTE:	The PLC w both words may be son	till receive both words with each discrete read, but it is not guaranteed that will be transferred as a unit. Both words will get transferred, but there ne delay between the two.
NOTE:	<i>For the PL</i> allow componies only.	$C-2^{\text{(B)}}$ series, you must use a 1772-SD2 scanner and the <i>PLC-2</i> ^(B) system to munication with the HI 2151WC via block transfer. Use block transfers
NOTE:	For the SL cation with transfer.	C 5/02 [®] or above processors, you must use a 1747-SN to allow communi- the HI 2151WC via discrete transfer. The 1747-SN does not support block

5 = Dipswitch	bit 0	Reserved for future use
Settings (interior)	bit 1	Enables gross weight output on RS232 port once per second
Status Byte	bit 2	Calibration lockout for NTEP (Legal for Trade) mode
-	bit 3	Ignore incoming serial checksums (RS232 port)
	bit 4	Peak force is result of averaged gross weight
	bit 5	NTEP (Legal for Trade) mode enable
	bit 6	Eliminate ">" on print out (RS232 port)
	bit 7	Designates instrument to be in "Blind" configuration
8 = MSB of 24 Bit	bit 0	bit 16 of weight data
Weight Value	bit 1	bit 17 of weight data
•	bit 2	bit 18 of weight data
	bit 3	bit 19 of weight data
	bit 4	sign bit 20
	bit 5	sign bit 21
	bit 6	sign bit 22
	bit 7	sign bit 23
9 = Sync Pulse	0-7	This byte increments every 50 milliseconds
-		(new data available)

Example of Screen Printout

ADDRESS	17			0	ADDRE	SS 17			0
1:000	0000	0000	0000	0000	I:020	0100	0010	0011	1001
I:001	0000	0000	0000	0000	I:021	0000	0110	0000	0110
I:002	0000	0000	0000	0000	1:022	0000	0000	0000	0000
1:003	0000	0000	0000	0000	I:023	0000	0000	0000	0000
I:004	0000	0000	0000	0000	I:024	0000	0000	0000	0000
I:005	0000	0000	0000	0000	I:025	0000	0000	0000	0000
I:006	0000	0000	0000	0000	I:026	0000	0000	0000	0000
I:007	0000	0000	0000	0000	I:027	0000	0000	0000	0000
I:010	0000	0000	0000	0000	1:030	0000	0000	0000	0000
I:011	0000	0000	0000	0000	I:031	0000	0000	0000	0000
I:012	0000	0000	0000	0000	I:032	0000	0000	0000	0000
I:013	0000	0000	0000	0000	1:033	0000	0000	0000	0000
I:014	0000	0000	0000	0000	I:034	0000	0000	0000	0000
I:015	0000	0000	0000	0000	I:035	0000	0000	0000	0000
I:016	0000	0000	0000	0000	I:036	0000	0000	0000	0000
I:017	0000	0000	0000	0000	1:037	0000	0000	0000	0000
CHANGE RADIX				SPECIFY ADDRESS	6	NEXT FILE	PREV FILE	FORCE MONITOR	
F1				F5	F	8 F9			

The addresses begin with the letter I not the number I.

CHAPTER 5 - BLOCK TRANSFERS

About Block Transfers The ladder logic programmer is able to exchange blocks of data with a 1/4 rack device via Block Transfer instructions in the ladder logic program. A Write Block Transfer is used to send commands and data to the Weight Controller, and a Read Block Transfer is used to collect acknowledgments and data from the Weight Controller. It is recommended that those front panel functions to be controlled via the Remote I/O network be locked from front panel control. Consult the HI 2151WC manuals for more information.

> To utilize 20 bit resolution, the Ladder Logic program must synchronize the use of Block Transfer data to insure block integrity. Synchronization is accomplished by not using block data between the time block transfer is enabled and done (EN and DN bits). Of course, data can be moved to another buffer where it can be accessed while the next block transfer is in progress. The structure of the four byte numeric format for all weight parameters except totalized weight is as follows:

BYTE 1	BYTE 0 upper 4 bits	Byte 0 lower 4 bits	BYTE 3	BYTE 2
Sign bits	Sign bits	Weight bits	Weight bits	Weight bits
	(all 1's or 0's)	19-16	15-8	7-0

TABLE 5-1: FOUR BYTE NUMERIC FORMAT FOR WEIGHT PARAMETERS

NOTE:	The most significant word is located before the least significant word in the block I/O transfer.
NOTE:	Negative values are sent in "two's complement" form.
NOTE:	The maximum block size is 51 words.
NOTE:	Block writes cannot be performed while the instrument is in the calibration mode. The calibration must be sealed by pressing enter at Endcal.
	Totalized weight uses all 32 bits available in the two words to represent unsigned data. the block transfer commands and formats are listed in the following tables. The Block Read commands are followed by the Block Write commands. When writing information to the weight con- troller be sure to send zeros (0's) to all words and bits marked as "reserved for future use". This will aid in achieving upward compatibil- ity to future enhancements to the command set. For additional informa- tion on the function of each parameter in the tables below, consult the HI 2151 Installation and Operation manuals.
Block Read Commands	All block read commands are initiated by the ladder logic program per- forming a block write to the weight controller with the desired block command number in the first byte position of the block. the PLC then performs a block read and the weight controller will return the desired

information with the read command number repeated in the first byte of the block returned. If a data error is detected, an error code "99" is in the first byte of the returned block.

NOTE:

All block reads are initiated by performing a block write.

NOTE:

A returned value of "99" (decimal) indicates an error.

Block Read Command Number 1: Full Status and Weight Data

BLOC	K READ CO	DMMAND NUMBER 1: Full status and weight data		071.07
WORI	WORD DEFINITIONS:			WORD
Comm	nand numbe	r: A value of 1 (decimal)	1	0
	bit 0	1		
	bit 1	0		
	bit 2	0		
	bit 3	0		
	bit 4	0		
	bit 5	0		
	bit 6	0		
	bit 7	0		
Indica	tor Group 1	Status		
	bit 8	Rate-of-Change currently displayed		
	bit 9	Setpoint RElay #2 active		
	bit 10	Setpoint Relay #1 active		
	bit 11	Peak Force (weight) currently displayed		
	bit 12	Totalized weight currently displayed		
	bit 13	Reserved for future use		
	bit 14	Reserved for future use		
	bit 15	Reserved for future use		
Indica	tor Group 2	Status	1	1
	bit 0	Weight currently displayed in pounds units		
	bit 1	Zero Track feature enabled		
	bit 2	Reserved for future use		
	bit 3	Current gross weight = 0		
	bit 4	Weight in motion, i.e. changing		
	bit 5	Gross weight currently displayed		
	bit 6	Net weight currently displayed		
	bit 7	Weight currently displayed in Kilogram units		
Dipsw	itch Settings	s (exterior) Status		
-	bit 8	Re-calibrate toggle		
	bit 9	Option menu keypad lockout		
	bit 10	Setpoint menu keypad lockout		
	bit 11	Lb/Kg, Net/Gross, Tare, Zero keypad lockout		
	bit 12	Zero tracking enable		
	bit 13	Reserved for future use		
	bit 14	RS232 command lockout		
	bit 15	Multi-Drop enable (RS-422 only)		
Note:	When the H dipswitches information.	II 2151WC is configured as a blind unit, the status of the are not visible. See section on blind operation for more		

TABLE 5-2: BLOCK READ COMMAND NUMBER 1: FULL STATUS AND WEIGHT DATA

BLOCK READ	BLOCK READ COMMAND NUMBER 1: Full status and weight data					
WORD DEFINI	TIONS:	#WORDS	WORD			
Dipswitch Settin	igs (interior) Status	1	2			
bit 0	Reserved for future use					
bit 1	Enables gross weight output on RS232 port once per second					
bit 2	Calibration lockout for NTEP (Legal for Trade) mode					
bit 3	Ignore incoming serial checksums (RS232 port)					
bit 4	Peak force is result of averaged gross weight					
bit 5	NTEP (Legal for Trade) mode enable					
bit 6	Eliminate ">" on print out (RS232 port)					
bit 7	Reserved for blind unit toggle					
Remote Functio	n Status					
bit 8	Force display to Rate-of-Change mode					
bit 9	Add current net weight to total					
bit 10	Hold value on display					
bit 11	Hold option card updates					
bit 12	Force display to Net weight mode					
bit 13	Toggle lbs/kg					
bit 14	Acquire Tare					
bit 15	Print request (RS232 and BCD ports)					
Note: When the	HI 2151WC is configured as a blind unit, the status of the					
dipswitche	es are not visible. See section on blind operation for more					
informatio	n.					
Rate-of-Change		2	3			
Peak force of w	eight	2	5			
Total weight in a	accumulator	2	7			
Gross Weight		2	9			
Net Weight		2	11			
Tare Value		2	13			
Note: All weight calibratior	data is in the units (lbs., kgs.) which were used at the time of n.					
TOTAL NUMBE	R OF WORDS	15				

TABLE 5-2: BLOCK READ COMMAND NUMBER 1: FULL STATUS AND WEIGHT DATA

Block Read Command Number 2: Setpoint Relay Parameter

BLOCK READ COMMAND NUMBER 2: Setpoint Relay Parameters					
WORD DEFINIT	IONS:	#WORDS	START WORD		
Command numb	er: A value of 2 (decimal)	1	0		
bit 0	0				
bit 1	1				
bit 2	0				
bit 3	0				
bit 4	0				
bit 5	0				
bit 6	0				
bit 7	0				
Indicator Group 2	2 Status				
bit 8	Weight currently displayed in pounds units				
bit 9	Zero Track feature enabled				
bit 10	Reserved for future use				
bit 11	Current gross weight = 0				
bit 12	Weight in motion, i.e. changing				
bit 13	Gross weight currently displayed				
bit 14	Net weight currently displayed				
bit 15	Weight currently displayed in kilogram units				
Note: A returned	value of "99" (decimal) indicates an error.				
Relay Status		1	1		
bit 0	Relay #8 status (on/off)				
bit 1	Relav #7 status (on/off)				
bit 2	Relay #6 status (on/off)				
bit 3	Relay #5 status (on/off)				
bit 4	Relav #4 status (on/off)				
bit 5	Relav #3 status (on/off)				
bit 6	Relay #1 status (on/off)				
bit 7	Relay #2 status (on/off)				
bit 8 - 15	Setpoint description byte A (See Table 5-4 & 5-5)				
bits 0-7 bits 8-15	Setpoint description byte B (See Table 5-4 & 5-5)	1	2		
513 0-13					
Deadband value	for setpoint #1	2	3		
Deadband value	for setpoint #2	2	5		
Deadband value	for setpoint #3	2	1		
Deadband value	for setpoint #4	2	9		
Deadband value	for setpoint #5	2	12		
Deadband value	for setpoint #6	2	13		
Deadband value	for setpoint #7	2	10		
Deaubariu value		2	17		
Preact value for	setpoint #1	2	19		
Preact value for	setpoint #2	2	21		
Preact value for	setpoint #3	2	23		
Preact value for	setpoint #4	2	25		
Preact value for	setpoint #5	2	27		
Preact value for	setpoint #6	2	29		
Preact value for	setpoint #7	2	31		
Preact value for	setpoint #8	2	33		

BLOCK READ COMMAND NUMBER 2: Setpoint Relay Parameters	#WORDS	START
Setpoint value for setpoint #1	2	35
Setpoint value for setpoint #2	2	37
Setpoint value for setpoint #3	2	39
Setpoint value for setpoint #4	2	41
Setpoint value for setpoint #5	2	43
Setpoint value for setpoint #6	2	45
Setpoint value for setpoint #7	2	47
Setpoint value for setpoint #8	2	49
TOTAL NUMBER OF WORDS	51	

TABLE 5-3: BLOCK READ COMMAND NUMBER 2: SETPOINT RELAY PARAMETERS

	Peak Force	Net Weight	Gross Weight	Rate-of-Change	Totalizer
Word 1, bits 8 - 15	0	0	0	0	1
Word 2, bits 0 - 7	0	0	1	1	0
Word 2, bits 8 - 15	0	1	0	1	0

TABLE 5-4: SETPOINT DESCRIPTION BYTES

The three setpoint description bytes are constructed by first reading the table above to determine the 1 and 0 pattern representing the weighing parameter you would like the setpoint to monitor, then writing that pattern below under the appropriate relay number. When patterns have been written for all desired relays then read bytes A, B, and C across from left to right.

SETPOINT DESCRIPTION BYTES								
	Relay 8	Relay 7	Relay 6	Relay 5	Relay 4	Relay 3	Relay 2	Relay 1
Word 1, bits 8-15								
Word 2, bits 0-7								
Word 2, bits 8-15								

TABLE 5-5: SETPOIINT DESCRIPTION BYTES

Example of Proper Setpoint Description Bytes	The proper setpoint description bytes for the following desired Relay types are as follows:				
	Relay 1 = Gross Relay 2 = Net Relay 3 = Rate-of-Change Relay 4 = Peak Relay 5 = Totalizer Relay 6 = Gross Relay 7 = Gross	Word 1, bits 8 - 15 = 0001 0000 = 10 (hex) Word 2, bits 0 - 7 = 1110 0101 = E5 (hex) Word 2, bits 8 - 15 = 0000 0110 = 06 (hex)			

Relay 8 = Gross

Block Read Command Number 3: Instrument Identification and Diagnostics

BLOCK READ COMMAND NUMBER 3: Instrument Identification and Diagnostics					
WORD DEFINIT	IONS:	#WORDS	WORD		
Command numb	er: A value of 3 (decimal)	1	0		
bit 0	1				
bit 1	1				
bit 2	0				
bit 3	0				
bit 4	0				
bit 5	0				
bit 6	0				
bit 7	0				
Instrument type	by model number				
	A value of 1, if set for the HI 2151				
DIT 9-15	Reserved for future use				
Firmware revisio	n level: (ASCII format, i.e. 65 = A)	1	1		
Zero calibration analog to digital converter raw counts:		2	2		
Span calibration analog to digital converter raw counts: 2 4			4		
TOTAL NUMBER	R OF WORDS	6			

TABLE 5-6: BLOCK READ COMMAND NUMBER 3: INSTRUMENT IDENTIFICATION AND DIAGNOSTICS

Block Read Command Number 4: Read Tare Value

BLOCK READ COMMAND NUMBER 4: Read Tare Value					
WORD DEFINITI	ONS:	#WORDS	WORD		
Command numb	er: A value of 4 (decimal)	1	0		
bit 0	0				
bit 1	0				
bit 2	1				
bit 3	0				
bit 4	0				
bit 5	0				
bit 6	0				
bit 7	0				
bits 8 - 15	Reserved for future use				
Tare Value 2			1		
TOTAL NUMBER	OF WORDS	3			

TABLE 5-7: BLOCK READ COMMAND NUMBER 4: READ TARE VALUE

Block Read Command Number 5: Calibration Parameters

BLOCK READ C	DMMAND NUMBER 5: Calibration Parameters			OTADT	
WORD DEFINITI	WORD DEFINITIONS: #WORDS				
Command number	er: A value of 5 (decimal)		1		0
bit 0	1				
bit 1	0				
bit 2	1				
bit 3	0				
bit 4	0				
bit 5	0				
bit 6	0				
bit 7	0				
bits 8 - 15	Reserved for future use				
Units of Measure			1		1
bits 0 - 7	A value of 0 for pounds, or 1 for kilograms				
Decimal point por	sition (places to the right of the decimal)				
bits 8 - 15	A value from 0 to 5				
Totalizer decimal	Totalizer decimal point position (places to the right of the decimal) 1 2				
bis 0 - 7 A value from 0 to 5					
C2™, Second Generation Calibration					
bits 8 - 15	Load Cell Count				
Display Graduation	on size ('count by): A value of 1,2,5,10,20,50,100,200, or 500		1		3

BLOCK READ COMMAND NUMBER 5: Calibration Parameters					
WORD DEFINITIONS: #V	WORDS	START WORD			
Motion Tolerance: A sixteen bit value representing the low 16 bits of the 20 bit internal wei range	ighing	1	4		
Zero Tolerance: A sixteen bit value representing the low 16 bits of the 20 bit internal weighi	ing range	1	5		
Number of readings averaged: A value from 1 to 200 Note: Number of averages will temporarily read 200 if the instrument was in the CAL ment this block read occurred.	u while	1	6		
Span weight value or $C2^{\ensuremath{\mathbb{R}}}$, Second Generation reference point value"		2	7		
Scale Capacity (Full limit of scale): A 20 bit number in proper integer format		2	9		
Mid-point Linearity Calibration Value: A 20 bit number in proper integer format		2	11		
TOTAL NUMBER OF WORDS		13			

TABLE 5-8: BLOCK READ COMMAND NUMBER 5: CALIBRATION PARAMETERS

Block Read Command Number 6: Configuration of Rate-of-Change

BLOCK READ C	OMMAND NUMBER 6: Configuration of Rate-of-Change		START
WORD DEFINITI	ONS:	#WORDS	WORD
Command number	er: A value of 6 (decimal)	1	0
bit 0	0		
bit 1	1		
bit 2	1		
bit 3	0		
bit 4	0		
bit 5	0		
bit 6	0		
bit 7	0		
bits 8 - 15	Reserved for future use		
Displayed Rate-o	f-Change time units: A value of 0 to 2 (0=sec, 1=min, 2=hr)	1	1
Rate-of-Change t	imebase evaluation period in seconds	1	2
0 = 1 secor	and $4 = 5$ seconds $8 = 15$ seconds $12 = 240$ seconds		
1 = 2 secor	nds 5 = 6 seconds 9 = 30 seconds 13 = 450 seconds		
2 = 3 secor	nds 6 = 10 seconds 10 = 60 seconds 14 = 900 seconds		
3 = 4 secor	nds 7 = 12 seconds 11 = 120 seconds 15 = 1800 seconds		
TOTAL NUMBER	OF WORDS	3	

TABLE 5-9: BLOCK READ COMMAND NUMBER 6: CONFIGURATION OF RATE-OF-CHANGE

Block Read Command Number 7: BCD Output Configuration

BLOCK READ COMMAND NUMBER 7: BCD Output Configuration			
WORD DEFINIT	IONS:	#WORDS	WORD
Command numb	er: A value of 7 (decimal)	1	0
bit 0	1		
bit 1	1		
bit 2	1		
bit 3	0		
bit 4	0		
bit 5	0		
bit 6	0		
bit 7	0		
Format of output			
bit 8	If set, will update BCD output when "print" button or remote function is activated		
bit 9	Reserved for future use		
bit 10	If set, will output weight data currently displayed		
bit 11	If set, will output tare value		
bit 12	If set, will output net weight		
bit 13	If set, will output gross weight		
bit 14-15	Reserved for future use		
Reserved for future use 1 1			
TOTAL NUMBER OF WORDS 2			

TABLE 5-10: BLOCK READ COMMAND NUMBER 7: BCD OUTPUT CONFIGURATION

Block Read Command Number 8: Configuration of Analog Output

BLOCK READ O	COMMAND NUMBER 8: Configuration of Analog Output		
WORD DEFINIT	WORD DEFINITIONS:		START WORD
Command numb	per: A value of 8 (decimal)	1	0
bit 0	0		
bit 1	0		
bit 2	0		
bit 3	1		
bit 4	0		
bit 5	0		
bit 6	0		
bit 7	0		
Weight parameter to be transmitted			
bits 8 - 15	A value from 0 to 4 (0 = Gross, 1 = Net, 2 = Rate-of-Change,		
	3 = Peak Force, 4 = Totalize amount)		

BLOCK READ COMMAND NUMBER 8: Configuration of Analog Output		
WORD DEFINITIONS:	#WORDS	START WORD
Weight value represented by a zero scale analog output:	2	1
Weight value represented by a full scale analog output:	2	3
TOTAL NUMBER OF WORDS	5	

TABLE 5-11: BLOCK READ COMMAND NUMBER 8: CONFIGURATION OF ANALOG OUTPUT

Block Read HI 2151/20WC Only. Command Number 9: Configuration of Standard RS232 Port (HI 2151/20WC Only)

BLOCK READ COMMAND NUMBER 9: Configuration of Standard RS232 Port			
WORD DEFINITI	ONS:	#WORDS	WORD
Command number bit 0 bit 1 bit 2 bit 3 bit 4 bit 5 bit 6 bit 7 bits 8 - 15	er: A value of 9 (decimal) 1 0 0 1 0 0 0 0 Reserved for future use	1	0
Format of Commu bit 0 bit 1 bit 2 bit 3 bit 4 bit 5 bit 6 bit 7 bits 8 - 15	Inication: Print initiation (If configured as printer. 1 = print button 0 = continuous. If configured as bi-directional: 0 = print button, 1 = altered print). Setpoint, Deadbands, and Preact values transmitted Rate-of-Change transmitted Tare weight transmitted Net weight transmitted Gross weight transmitted Reserved for future use Reserved for future use Reserved for future use	1	1
Port Configuration bits 0 - 7 Baud Rate bits 8 - 15	A value of 0 or 1 [0=Bi-Directional, 1 = Printer (output) only] A value of 0 to 5 (0 = 600, 1 = 1200, 2 = 2400, 3 = 4800, 4 = 9600, 5 = 19200)	1	2
Parity bits 0 - 7 Stop Bits bits 8 - 15 *Note: Parameter	A value of 0 to 2 (0=None, 1 = 1 = Even, 2 = Odd)* A value of 0 or 1 (0=one stop bit, 1 = two stop bits)* s are not used in the HI 2151/30WC	1	3

BLOCK READ COMMAND NUMBER 9: Configuration of Standard RS232 Port	STADT	
WORD DEFINITIONS:	#WORDS	WORD
Word Length bits 0 - 7 A value of 0 or 1 [0 = seven bits, 1 = eight bits* Handshake Control bits 8 - 15 A value of 0 or 1 (0 = Hardware, 1 = Software *Note: Parameters are not used in the HI 2151/30WC	1	4
Echo bits 0 - 7 A value of 0 or 1 (0= Off, 1 = On) Device Address bits 8 - 15 A value from 0 to 99	1	5
TOTAL NUMBER OF WORDS	6	

TABLE 5-12: BLOCK READ COMMAND NUMBER 9: CONFIGURATION OF STANDARD RS232 PORT

Block Read Command Number 10: Sticker Value HI 2151/20WC Only.

NOTE:

Sticker Value is not used in the HI 2151/30WC

BLOCK READ C			
WORD DEFINITIONS:		#WORDS	WORD
Command number	er: A value of 10 (decimal)	1	0
bit 0	0		
bit 1	1		
bit 2	0		
bit 3	1		
bit 4	0		
bit 5	0		
bit 6	0		
bit 7	0		
bits 8 - 15	Reserved for future use		
Sticker Value A 20 bit nu	mber in proper integer format	2	1
TOTAL NUMBER OF WORDS		3	

TABLE 5-13: BLOCK READ COMMAND NUMBER 10: STICKER VALUE

Block Read Command Number 11: Auto Zero Tolerance

BLOCK READ COMMAND NUMBER 11: Auto Zero Tolerance				
WORD DEFINITIONS:		#WORDS	START WORD	
Command number	er: A value of 11 (decimal)	1	0	
bit 0	1			
bit 1	1			
bit 2	0			
bit 3	1			
bit 4	0			
bit 5	0			
bit 6	0			
bit 7	0			
bits 8 - 15	Reserved for future use			
Auto Zero Tolerance		1	1	
A 16 bit nur	A 16 bit number in proper integer format			
TOTAL NUMBER OF WORDS 2				

TABLE 5-14: BLOCK READ COMMAND NUMBER 11: AUTO ZERO TOLERANCE

Block Read Command Number 12: Integrated Technician HI 2151/30WC Only.

NOTE:

Integrated Technician is not used with the HI 2151/20WC

BLOCK READ COMMAND NUMBER 12: Integrated Technician				
WORD DEFINITI	ONS:	#WORDS	WORD	
Command numb	er: A value of 12 (decimal)	1	0	
bit 0	0			
bit 1	0			
bit 2	1			
bit 3	1			
bit 4	0			
bit 5	0			
bit 6	0			
bit 7	0			
bit 8	Reserved for future use			
Excitation Monito	r	1	1	
On/Off				
bits 0 - 7	A value of 0 or 1 (0 = Off, 1 = On)			
OK/ERR				
bits 8 - 15	A value of 0 or 1 (o = OK, 1 = ERR)			
TOTAL NUMBER	R OF WORDS	2		

TABLE 5-15: BLOCK READ COMMAND NUMBER 12: INTEGRATED TECHNICIAN

Block Transfer Read Example This routine is set up to be used with the HI 2151WC series weight controllers. It is a Block Transfer Read (BTR) sub-routine, currently configured to do a BTR 2 of the relay setpoint data. The block length is the only value which needs to be changed to use other block transfer read types. This routine will continually read the HI 2151WC as long as it is running.

N21:0 will have a 2, to request a block transfer read #2.





Block Write Commands

About Block Write Commands	After the PLC performs a block transfer write, a block read should be performed to evaluate the response code from the HI 2151 to verify that the data was received and implemented. The response word will either show a successful processing of the block or will indicate the first error encountered in processing of the data.
NOTE:	Setpoints, deadbands and preacts can all accept negative values. To enter negative values, use the "twos complement" method.
NOTE:	Block Writes cannot be performed while the instrument is in calibration mode. The calibration must be sealed by pressing enter at Endcal.

Block Write Command Number 51: Activate Scale Functions

BLOCK WRITE	ECOMMAND NUMBER 51: Activate Scale Functions		CTADT	
WORD DEFINI	TIONS:	#WORDS	WORD	
Command num	ber: A value of 51 (decimal)	1	0	
bit 0	1			
bit 1	1			
bit 2	0			
bit 3	0			
bit 4	1			
bit 5	1			
bit 6	0			
bit 7	0			
Remote Function	ons Byte			
bit 8	Acquire TARE (Set tare value = current gross weight)*			
bit 9	Initiates print on standard RS232 or optional BCD port*			
bit 10	Add current Net weight to Total* [!]			
bit 11	Clear Peak Hold register*!			
bit 12	Clear Totalizer Accumulation*!			
bit 13	Zero the instrument*			
bit 14	Enable Zero Tracking (Blind Unit Only)			
bit 15	Reserved for future use			
*Note [.] The bit r	*Note: The bit must be toggled to activate this function			
Note: Only active if the instrument is ordered with this ontion				
TOTAL NUMBER OF WORDS 1				

TABLE 5-16: BLOCK WRITE COMMAND NUMBER 51: ACTIVATE SCALE FUNCTIONS

Block Write Command Number 52: Downloading Setpoint Relay Parameters

BLOCK WRITE COMMAND NUMBER 52:Downloading Setpoint Relay Parameters				
WORD DEFINITI	ONS: #WORDS		START WORD	
Command number	er: A value of 52 (decimal)	1		0
bit 0	0			
bit 1	0			
bit 2	1			
bit 3	0			
bit 4	1			
bit 5	1			
bit 6	0			
bit 7	0			
bits 8 - 15	Reserved for future use			
Setpoint Enable:				
bit 8	Enable Relay #8 to evaluate weight			
bit 9	Enable Relay #7 to evaluate weight			
bit 10	Enable Relay #6 to evaluate weight			
bit 11	Enable Relay #5 to evaluate weight			
bit 12	Enable Relay #4 to evaluate weight			
bit 13	Enable Relay #3 to evaluate weight			
bit 14	Enable Relay #1 to evaluate weight*			
bit 15	Enable Relay #2 to evaluate weight*			
*Note: Notice rela	ys 1 and 2 are not in numerical sequence			
Force Relay Statu	IS*	1		1
bit 0	Turn relay #8 on regardless of weight (setpoint enable bit must be 0)			
bit 1	Turn relay #7 on regardless of weight (setpoint enable bit must be 0)			
bit 2	Turn relay #6 on regardless of weight (setpoint enable bit must be 0)			
bit 3	Turn relay #5 on regardless of weight (setpoint enable bit must be 0)			
bit 4	Turn relay #4 on regardless of weight (setpoint enable bit must be 0)			
bit 5	Turn relay #3 on regardless of weight (setpoint enable bit must be 0)			
bit 6	Turn relay #1 on regardless of weight (setpoint enable bit must be 0)			
bit 7	Turn relay #2 on regardless of weight (setpoint enable bit must be 0)			
*Note: Force relay trigger on a weigh	y on/off is only available over this interface. If you desire to manually set a relay to at parameter, make sure force relay bit is set to 0.			
bits 8 - 15	Setpoint description byte A (See Table 5-18 & 5-19)			
bits 0 - 7	Setpoint description byte B (See Table 5-18 & 5-19)	1		2
bits 8 - 15	Setpoint description byte C (See Table 5-18 & 5-19)			
Deadband value	for setpoint #1	2		3
Deadband value	for setpoint #2	2		5
Deadband value	for setpoint #3	2		7
Deadband value	for setpoint #4	2		9
Deadband value	for setpoint #5	2		11
Deadband value	for setpoint #6	2		13
Deadband value	for setpoint #7	2		15
Deadband value	for setpoint #8	2		17

BLOCK WRITE COMMAND NUMBER 52: Downloading Setpoint Relay Parameters			
WORD DEFINITIONS:	#WORDS	START WORD	
Preact value for setpoint #1 Preact value for setpoint #2 Preact value for setpoint #3 Preact value for setpoint #4 Preact value for setpoint #5 Preact value for setpoint #6 Preact value for setpoint #7 Preact value for setpoint #8		2 2 2 2 2 2 2 2 2 2 2 2	19 21 23 25 27 29 31 33
Setpoint value for setpoint #1 Setpoint value for setpoint #2 Setpoint value for setpoint #3 Setpoint value for setpoint #4 Setpoint value for setpoint #5 Setpoint value for setpoint #6 Setpoint value for setpoint #7 Setpoint value for setpoint #8		2 2 2 2 2 2 2 2 2 2 2 2	35 37 39 41 43 45 47 49
TOTAL NUMBER OF WORDS		51	

TABLE 5-17: BLOCK WRITE COMMAND NUMBER 52: DOWNLOADING SETPOINT RELAY PARAMETERS

NOTE:

Deadband must be numerically larger than preact.

	Peak Force	Net Weight	Gross Weight	Rate-of-Change	Totalizer
Word 1, bits 8 - 15	0	0	0	0	1
Word 2, bits 0 - 7	0	0	1	1	0
Word 2, bits 8 - 15	0	1	0	1	0

TABLE 5-18: SETPOINT DESCRIPTION BYTES

The three setpoint description bytes are constructed by first reading the table above to determine the 1 and 0 pattern representing the weighing parameter you would like the setpoint to monitor, then writing that pattern below under the appropriate relay number. When patterns have been written for all desired relays then read bytes A, B, and C across from left to right.

SETPOINT DESCRIPTION BYTES								
	Relay 8	Relay 7	Relay 6	Relay 5	Relay 4	Relay 3	Relay 2	Relay 1
Word 1, bits 8-15								
Word 2, bits 0-7								
Word 2, bits 8-15								

TABLE 5-19: SETPOIINT DESCRIPTION BYTES

Example of Proper Setpoint Description Bytes The proper setpoint description bytes for the following desired Relay types are as follows:

Relay 1 = Gross

Relay 2 = Net Word 2, bits $0 - 7 = 1110\ 0101 = E5$ (hex) Relay 3 = Rate-of-Change Word 2, bits $8 - 15 = 0000\ 0110 = 06$ (hex) Relay 4 = Peak Relay 5 = Totalizer Relay 6 = Gross Relay 7 = Gross Relay 8 = Gross

Block Write Command Number 53: Send Tare Value

BLOCK WRITE COMMAND NUMBER 53:Send Tare Value				
WORD DEFINITIONS:		#WORDS	START WORD	
Command numb	er: A value of 53 (decimal)	1	0	
bit 0	1			
bit 1	0			
bit 2	1			
bit 3	0			
bit 4	1			
bit 5	1			
bit 6	0			
bit 7	0			
bit 8 -15	Reserved for future use			
Tare Value		2	1	
TOTAL NUMBER	R OF WORDS	3		

TABLE 5-20: BLOCK WRITE COMMAND NUMBER 53: SEND TARE VALUE

Block Write Command Number 54: Scale Calibration Action

BLOCK WRITE	COMMAND NUMBER 54: Scale Calibration Action		
WORD DEFINI	TIONS:	#WORDS	START WORD
Command num	ber: A value of 54 (decimal)	1	0
bit 0	0		
bit 1	1		
bit 2	1		
bit 3	0		
bit 4	1		
bit 5	1		
bit 6	0		
bit 7	0		
Remote Functio	ins Ryte		
hit 8	Setting then clearing this bit tells the instrument that current		
	weight is an empty scale.		
bit 9	Setting then clearing this bit tells the instrument that current		
	weight is span weight.		
bit 10	Setting then clearing this bit stores critical data in the Secure		
	Memory Module.		
bit 11	Setting then clearing this bit restores critical data from the		
	Secure Memory Module.		
bit 12	Setting then clearing this bit tells the instrument that current		
	weight is Midpoint Linearity value.		
bit 13	Reserved for future use		
bit 14	Setting then clearing this bit tells the instrument that current		
	weight is the C2™ reference point.		
bit 15	Reserved for future use		
TOTAL NUMBE	R OF WORDS	1	

TABLE 5-21: BLOCK WRITE COMMAND NUMBER 54: SCALE CALIBRATION ACTION

Block Write Command Number 55: Calibration Parameters

BLOCK WRITE COMMAND NUMBER 55: Calibration Parameters					
WORD DEFINITIONS:	#WORDS	WORD			
Command number: A value of 55 (decimal) bit 0 1 bit 1 1 bit 2 1 bit 3 0 bit 4 1 bit 5 1 bit 6 0 bit 7 0 bit 8 - 15 Reserved for future use	1	0			
Units of Measure: bits 0 - 7 0 = pounds, 1 = kilograms Decimal point position (places to right of decimal): bits 8 - 15 A value from 0 to 4	1	1			
Totalizer decimal point position (places to right of decimal): bits 0 - 7 A value from 0 to 4 C2 [™] , Second Generation Calibration bits 8 - 15 Load Cell Count (set to zero for Hard Cal)	1	2			
Display Graduation Size ("count by"): A value of 1,2,5,10,20,50,100,200 or 500	1	3			
Motion Tolerance: A sixteen bit value representing the lower 16 bits of the 20 bit internal weighing range	1	4			
Zero Tolerance: A sixteen bit value representing the lower 16 bits of the 20 bit inter- nal weighing range	1	5			
Number of readings averaged: A value from 1 to 200	1	6			
Span weight value (Use one of the following methods. Method one, with C2, Sec- ond Generation Calibration: Use the C2 reference point when using C2 load cells. Method two: use test weights for calibration) A 20 bit number in proper integer for- mat	2	7			
Scale Capacity (Full limit of scale): A 20 bit number in proper integer format	2	9			
Mid-point Linearity calibration value: A 20 bit number in proper integer format	2	11			
TOTAL NUMBER OF WORDS	13				

TABLE 5-22: BLOCK WRITE COMMAND NUMBER 55: CALIBRATION PARAMETERS

Block Write Command Number 56: Configuration of Rate-of-Change

BLOCK WRITE COMMAND NUMBER 56: Configuration of Rate-of-Change				
WORD DEFINITI	ONS:	#WORDS	WORD	
Command number	er: A value of 56 (decimal)	1	0	
bit 0	0			
bit 1	0			
bit 2	0			
bit 3	1			
bit 4	1			
bit 5	1			
bit 6	0			
bit 7	0			
bit 8 - 15	Reserved for future use			
Displayed Rate-o	f-Change time units: A value of 0 to 2 (0 = sec, 1 = min, 2 = hr)	1	1	
Rate-of-Change t 0 = 1 secor 1 = 2 secor 2 = 3 secor 3 = 4 secor	imebase evaluation period: A value of 0 to 15 from list below: d 4 = 5 seconds8 = 15 seconds12 = 240 seconds ds 5 = 6 seconds9 = 30 seconds13 = 450 seconds ds 6 = 10 seconds10 = 60 seconds14 = 900 seconds ds 7 = 12 seconds11 = 120 seconds15 = 1800 seconds	1	2	
TOTAL NUMBER	OF WORDS	3		

TABLE 5-23: BLOCK WRITE COMMAND NUMBER 56: CONFIGURATION OF RATE-OF-CHANGE

Block Write Command Number 57: BCD Output Configuration

BLOCK WRITE C	COMMAND NUMBER 57: BCD Output Configuration		OTADT
WORD DEFINITI	ONS:	#WORDS	WORD
Command number	er: A value of 57 (decimal)	1	0
bit 0	1		
bit 1	0		
bit 2	0		
bit 3	1		
bit 4	1		
bit 5	1		
bit 6	0		
bit 7	0		
Format of output:			
bit 8	If set, will update BCD output when "print" button or remote		
	function is activated.		
bit 9	Reserved for future use		
bit 10	If set, will output weight data currently displayed		
bit 11	If set, will output Tare Value		
bit 12	If set, will output Net Weight		
bit 13	If set, will output Gross Weight		
bit 14 - 15	Reserved for future use		
TOTAL NUMBER	OF WORDS	1	

TABLE 5-24: BLOC WRITE COMMAND NUMBER 57: BCD OUTPUT CONFIGURATION

Block Write Command Number 58: Configuration of Analog Output

NOTE:

This command is only active if this option is installed in the HI 2151WC

BLOCK WRITI	E COMMAND NUMBER 58: Configuration of Analog Output	#WORDS	START WORD
Command nun	nber: A value of 58 (decimal)	1	0
bit 0	0		
bit 1	1		
bit 2	0		
bit 3	1		
bit 4	1		
bit 5	1		
bit 6	0		
bit 7	0		
Weight parame bits 8 - 1 3 = Peak	eter to be transmitted 5 A value from 0 to 4 (0 = Gross, 1 = Net, 2 = Rate-of-Change, < Force, 4 = Totalized Amount)		

BLOCK WRITE COMMAND NUMBER 58: Configuration of Analog Output	#WORDS	START
Weight value represented by a zero scale analog output:	2	1
Weight value represented by a full scale analog output:	2	3
TOTAL NUMBER OF WORDS	1	

TABLE 5-25: BLOCK WRITE COMMAND NUMBER 58: CONFIGURATION OF ANALOG OUTPUT

Block WriteHI 2151/20WC Only.Command Number59: Configuration ofStandard RS232Port

BLOCK WRITE COMMAND NUMBER 59: Configuration of Standard RS232 Port START WORD DEFINITIONS: #WORDS WORD Command number: A value of 59 (decimal) 0 1 bit 0 1 bit 1 1 bit 2 0 bit 3 1 bit 4 1 bit 5 1 bit 6 0 bit 7 0 bits 8 - 15 Reserved for future use Format of Communication 1 1 bit 0 Print Initiation (1 = altered print, bit 6 must = 0)bit 1 Setpoint, Deadbands, and Preact values transmitted Rate-of-Change Transmitted bit 2 bit 3 Tare Weight Transmitted bit 4 Net Weight Transmitted Gross Weight Transmitted bit 5 Print initiation (0 = continuous, 1 = print button, bit 0 must = 0 bit 6 bit 7 - 15 Reserved for future use Port Configuration 1 2 bits 0 - 7 A value of 0 or 1 (0 = Bi-Directional, 1 = Printer (output) only) Baud Rate bits 8 - 15 A value of 0 to 5 (0 = 600, 1 = 1200, 2 = 2400, 3 = 4800, 4 = 9600, 5 = 19200 Parity 1 3 bits 0 - 7 A value of 0 to 2 (0 = None, 1 = Even, 2 = Odd)* Stop Bits bits 8 - 15 A value of 0 or 1 (0 = one stop bit, 1 = two stop bits)* *Note: Parameters not set by HI 2151/30 Word Length 1 4 bits 0 - 7 A value of 0 or 1 (0 = seven bits, 1 = eight bits)* Handshake Control bits 8 - 15 A value of 0 or 1 (0 = Hardware, 1 = Software) *Note: Parameters not set by HI 2151/30

BLOCK WRITE COMMAND NUMBER 59: Configuration of Standard RS232 Port					
WORD DEFINITIONS:	#WORDS	START WORD			
Echo bits 0 - 7 A value of 0 or 1 (0 = OFF, 1 = ON) Device Address bits 8 - 15 A value of 0 to 99	1	5			
TOTAL NUMBER OF WORDS	6				

TABLE 5-26: BLOCK WRITE COMMAND NUMBER 59: CONFIGURATION OF STANDARD RS232 PORT

Block Write Command Number 60: Sticker Value

NOTE:

Not used with the HI 2151/30WC

BLOCK WRITE (COMMAND NUMBER 60: Sticker Value	#WORDS	START WORD
Command numb	er: A value of 60 (decimal)	1	0
bit 0	0		
bit 1	0		
bit 2	1		
bit 3	1		
bit 4	1		
bit 5	1		
bit 6	0		
bit 7	0		
bits 8 - 15	Reserved for future use		
Sticker Value A 20 bit nu	mber in proper integer format	2	1
TOTAL NUMBER	R OF WORDS	3	

TABLE 5-27: BLOCK WRITE COMMAND NUMBER 60: STICKER VALUE

Block Write Command Number 61: Auto Zero Tolerance

BLOCK WRITECOMMAND NUMBER 61: Auto Zero Tolerance				
WORD DEFINITI	ONS:	#WORDS	WORD	
Command number	er: A value of 61 (decimal)	1	0	
bit 0	1			
bit 1	0			
bit 2	1			
bit 3	1			
bit 4	1			
bit 5	1			
bit 6	0			
bit 7	0			
bits 8 - 15	Reserved for future use			
Auto Zero Tolera	nce	1	1	
A 16 bit nui	A 16 bit number in proper integer format			
TOTAL NUMBER	R OF WORDS	2		

TABLE 5-28: BLOCK WRITE COMMAND NUMBER 61: AUTO ZERO TOLERANCE

Block Write Command Number 62: Waversaver/ Excitation Monitor HI 2151/30WC Only.

BLOCK WRITE COMMAND NUMBER 62: Waversaver/Excitation Monitor								
WORD DEFINITI	ONS:	#WORDS	WORD					
Command number	er: A value of 62 (decimal)	1	0					
bit 0	0							
bit 1	1							
bit 2	1							
bit 3	1							
bit 4	1							
bit 5	1							
bit 6	0							
bit 7	0							
Waversaver								
bits 8 - 15	Waversaver setting (1-5) (Error #87 returned if an error)							
Excitation Monito	r	1	1					
bit 0 bits 1 - 15	0 = Disable Excitation Monitor, 1 = Enable Excitation Monitor Reserved for future use							
TOTAL NUMBER								

TABLE 5-29: BLOCK WRITE COMMAND 62: WAVERSAVER/EXCITATION MONITOR

Block Transfer Write	This is a Block Transfer Write (BTW) sub-routine, currently config-
Example	ured to do a BTW 52 of the relay setpoint data. The block length is the
	only value which needs to be changed to use other block transfer write
	types. Once called, the routine will write the block until a return code
	of 06 (BTW OK) is sent.

A value of 70 is at N 11:60 B 3:0 will enable routine and is cleared when completed Valid BTW Data starts at N 11:0





Integer to Floating Point Routine

This example assumes the two words representing the desired weight value have been read with a block transfer read. They must also reside

as MSW in memory location N10:9, and as LSW in memory location N10:10. This routine works for all values except the totalizer.



All negative numbers are sent from the weight controller to the programmable controller in "twos complements"







Response and Error Codes

Each time the PLC performs a block write, it should then perform the response code block read. This block read will return two bytes. The first byte is the command number of the last block write performed. The second byte will be the response or error code returned. If the error code is a NACK (21) then the returned command number will be a 99.

BLOCK READ COMMAND NUMBER 70: Reading response code after a block write WORD DEFINITIONS	# WORDS	START WORD
Write command number (not 70 but the command number of the write performed) Bits 0 - 7	1	0
Response code from table below Bits 8-15		
TOTAL NUMBER OF WORDS	1	

TABLE 5-30: BLOCK READ COMMAND NUMBER 70: READING RESPONSE CODE AFTER A BLOCK WRITE

Block Read or Block	<u>Decimal</u>	HEX	Description
Write Error Codes	06	06	Acknowledge good data received
	21	15	NACK - illegal command
	22	16	Exceeded maximum legal words for block read and
			write
	23	17	In CAL mode
Block Write Error Codes	49	31	Scale in motion (for example: unable to calibrate while in motion)
	50	32	Current weight sensed over scale capacity (only functional for command 51)
	51	33	Weight not within zero tolerance, unable to zero
	52	34	Insufficient change in weight to calibrate span
	50	25	(display error #18)
	53	35	Decimal point places must be between 0 and 4
	54	36	Not a valid graduation size
	55	37	Motion value must be greater than graduation size
	30	38	Zero tolerance value must be greater than
	<i></i>	20	0 and positive.
	57	39	1 and 200
	58	3A	Span weight value, during calibration, must be
	59	3B	Scale capacity value must be positive
	60	3C	Midpoint linearity value must be positive
	61	3D	Rate-of-Change time units selection must be 0.1 or 2
	62	3E	Rate-of-Change time base out of range
	63	3F	BCD option not installed
	64	40	Invalid BCD card bit request
	65	41	Analog output not installed
	66	42	Analog output request must be between 0 and 4
Error Codes for	67	43	Invalid serial port (RS-232) format request
Block Write 59	68	44	Serial configuration values 0 or 1
	69	45	Baud rate request out of range
	70	46	Parity request out of range, must be 0,1,or 2

	71	47	Stop bits must be 0 or 1
	72	48	Data length must be 0 or 1
	73	49	Control (Hardware or Software) must be 0 or 1
	74	4A	Device Address must be between 0 and 99
	75	4B	Echo request must be a 0 or 1
Error Code for Block Write Command #53	76	4C	Tare greater than span
Error Code for Block Write Command #51	77	4D	Blind unit option only
Error Code for Block	96	60	Load cell count error
Write Command #55	97	61	No C2 [™] load cells found
	98	62	Load cell capacity/sensitivity error
	99	63	Load cell checksum error
	100	64	Too many significant digits after the decimal to be displayed.

CHAPTER 6 - CONVERSION CHARTS AND FORMULAS

Hex Chart

Use the Hex Chart to translate bit values to a hex value.

Relay Status Example For example the bit representative of the Relay status byte when setpoint relays 8,5,3, and 1 are on is (01101001). This eight bit value is represented by two four bit nibbles (0110 and 1001). Looking at the table we see this is equal to a Hex value of 69.

Bit 3	Bit 2	Bit 1	Bit 0					
Bit 7	Bit 6	Bit 5	Bit 4					
0	0	0	0	0				
0	0	0	1	1				
0	0	1	0	2				
0	0	1	1	3				
0	1	0	0	4				
0	1	0	1	5				
0	1	1	0	6				
0	1	1	1	7				
1	0	0	0	8				
1	0	0	1	9				
1	0	1	0	А				
1	0	1	1	В				
1	1	0	0	С				
1	1	0	1	D				
1	1	1	0	E				
1	1	1	1	F				

TABLE 6-1: HEX CHART

Bit #	Bit Status	Hex	Description
Bit 0	1 = On		Relay #8 status (on/off)
Bit 1	0 = Off		Relay #7 status (on/off)
Bit 2	0 = Off	9	Relay #6 status (on/off)
Bit 3	1 = On		Relay #5 status (on/off)

 TABLE 6-2: RELAY STATUS

Bit #	Bit Status	Hex	Description
Bit 4	0 = Off		Relay #4 status (on/off)
Bit 5	1 = On		Relay #3 status (on/off)
Bit 6	1 = On	6	Relay #1 status (on/off)
Bit 7	0 = Off		Relay #2 status (on/off)

TABLE 6-2: RELAY STATUS

Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Decimal Value	32768	16384	8192	4096	2048	1024	512	256	128	64	32	16	8	4	2	1
	ONE WORD															

TABLE 6-3: BINARY TO DECIMAL CHART

Block Write Example

The following is an example using block write #51 to zero the scale. Command #51 is made up of one word. Bits 0-7 represent the address or the command number (00110011 = 51). To activate the scale function, toggle bit #13. This creates a word which has a decimal value of 8,243.

	Bit #	0	0	1	0	0	0	0	0	0	0	1	1	0	0	1	1
Е																	

TABLE 6-4: BLOCK WRITE EXAMPLE

Math Conversion Programs	Math conversion routines, written in ladder logic convert the twenty bit integer data available from the HI 2151WC to a PLC floating point for- mat. Conversely, routines can convert from Floating Point to integer. To convert from integer to floating point, your ladder logic program would follow these steps:						
	Step 1. Convert the lower sixteen bits into a floating point number.						
	Step 2. Test the seventeenth bit (bit 16) and if set, add 65,536 to the floating point number.						
	Step 3. Test each subsequent bit and add the appropriate numeric value to the floating point number.						